

# Reinforcement of Structures with the Use of SLB Devices

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**Abstract** - The objective of this article is to study the control of the dynamic response of essential structures using SLB device. This type of dissipators has a high initial rigidity that allows it to operate from minimum values of displacement of the structure in the event of an earthquake. The theoretical and practical aspects related to the correct use of these dissipators are explained in detail.

The ideal seismic resistance of a structure is that it presents displacements of a rigid system and forces of a flexible system. A rigid - flexible - ductile system presents intermediate responses between a flexible system and a rigid system. The maximum use of this concept in a structure lies in optimizing the use of dissipators and conventional walls to adequately control drifts and at the same time shear forces do not increase considerably in a flexible system. The Anglo-American Clinic was chosen as the existing structure to verify the efficiency of the dissipators. The structure initially presented torsional irregularity and the maximum drifts in both directions exceeded the established limit. With the addition of SLB dissipators on strategically placed decoupled walls, the torsional irregularity was corrected and the maximum drifts were reduced.

**Keywords:** dissipators, slb devices, structures, reinforcement, torsional irregularity, shear link bozzo.

## 1. Introduction

The structure-dissipator system consists of a primary system capable of resisting both lateral and gravitational forces, and a secondary system, made up of the dissipators and their connections to the primary system, which are generally not designed to resist gravitational forces. The structure-dissipator system must be designed according to the type of use of the structure, its configuration, classification, location, type of seismic zone in which it is located, and the group to which it belongs based on its importance. The secondary system consists of the set of dissipators and the structural elements required to transfer the forces from the dissipators to the primary system. These elements must remain within their elastic behaviour range under forces associated with the collapse prevention limit state review [1].

Classical earthquake-resistant design involves high levels of structural redundancy to ensure the achievement of the required ductility, which results in increased costs and materials, as well as increased damage to structural elements. Seismic protection systems represent an advance in earthquake-resistant design because elements are specifically designed to withstand seismic loads and damage to the elements is significantly reduced [2].

## 2. Theoretical Framework

The ideal earthquake-resistant structure is one that presents displacements of a rigid system and forces of a flexible system. Energy dissipators concentrate the ductility demands in industrially manufactured elements.

The experimental curves for a scale model of a metal frame are incorporated on decoupled concrete walls in a vibrating table (Fig. 1 and Fig. 2). It is concluded that as the scale factor increases, a system with the level of forces of a flexible system and the level of displacements of a rigid system is achieved [3].

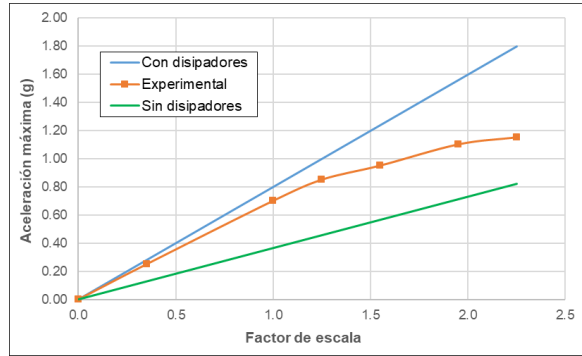


Fig. 1: Scale model of a steel frame incorporating decoupled walls. Base shear for different scale factors.

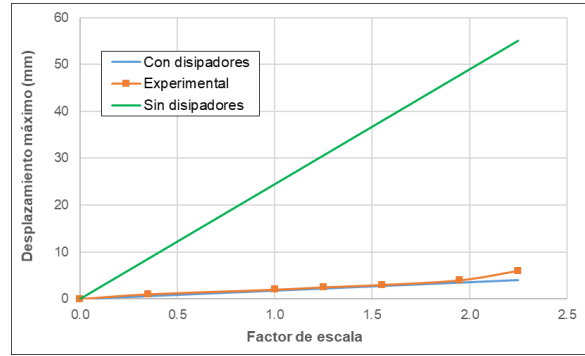


Fig. 2: Scale model of a steel frame incorporating decoupled walls. Maximum displacements for different scale factors.

A rigid-flexible-ductile system presents intermediate responses between a flexible system and a rigid system. The maximum use of this concept in a structure lies in optimizing the use of conventional dissipators and walls to adequately control the drifts and at the same time the shear forces do not increase considerably in a flexible system.

The SLB device is based on the localized increase of the building's ductility, allowing a significant reduction in the forces induced by a high-intensity earthquake.

The implementation of energy dissipation systems in a structure allows to modify the capacity design, making dampers the "weak elements" where the damage is concentrated and, therefore, where energy is dissipated. In this paper the metal dampers represented by the so-called Shear Link Bozzo devices are analysed. These devices were subjected to technological developments in the past 20 years, which led to the development of four generations of devices (Fig. 3) [4]. The geometry of a second generation SLB devices which is composed of four windows and a square frame (Fig. 4). In addition, the holes on the outside serve to be placed on the Chevron-type wind braces that the portico presents. The design of the steel elements will be carried out in accordance with the AISC 2016 Specification for Structural Steel Buildings [5].



Fig. 3: Shear Link Bozzo Devices

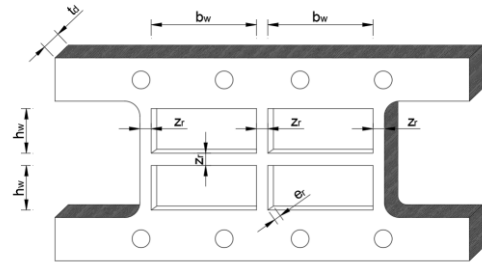


Fig. 4: Geometry of a second generation SLB device.

The frame of the SLB damper works as a column embedded at its ends, with stiffness  $k_r$ , while the windows with stiffness  $k_w$ . The stiffness of the frame and the windows are calculated using the following equations:

$$k_r = \frac{72 EI}{h_w^3} \quad (1)$$

$$k_w = \frac{4GA_w}{h_w} \quad (2)$$

Where  $I$  is the moment of inertia of the section;  $h_w$  is the height of a window;  $E$  is the modulus of elasticity of steel,  $G$  is the shear modulus and  $A_w$  represents the shear area of the windows.

An idealized bilinear model simulates the force-displacement behaviour of the SLB dissipator, with a stiffness  $k_1$  for the elastic range and  $k_2$  for the plastic range. In the elastic range, the windows and the frame work. In the plastic range, only the frame works, since the windows have degraded (Fig. 5).

$$k_1 = k_r + k_w \quad (3)$$

$$k_2 = \alpha k_r \quad (4)$$

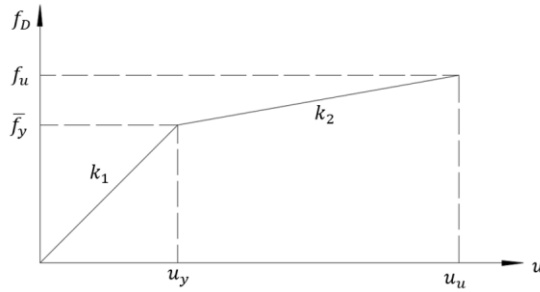


Fig. 5: Bilinear hysteresis curve of a SLB dissipators.

The value  $\alpha$  represents the coefficient that relates the plastic stiffness to the elastic stiffness. The window force  $f_w$  and the frame force  $f_r$  are related by their stiffnesses, and the yield force  $\bar{f}_y$  is equal to the sum of the window force plus the frame force.

$$f_r = \frac{k_r}{k_w} f_w \quad (5)$$

$$\bar{f}_y = f_w + f_r \quad (6)$$

### 3. Methodology

#### 3.1. Diagnosis of Structure State

A diagnosis consists of analysing the current state of a structure, after inspection, data collection and study of the same. In general, it includes the evaluation of the residual capacity, as well as the needs for action and its urgency. In case of damage, the nature, scope, and most probable cause of the same must be determined [6].

#### 3.2. Structural Modelling

Structural modelling is the process in which the structure is represented in order to analyse its behaviour. Modelling consists of:

- Definition of materials
- Definition of structural elements.
- Definition of load patterns.
- Definition of seismic weight.
- Modelling of the structure.
- Assignment of loads.
- Embedding of supports in the base.
- Assignment of diaphragms.
- Assignment of rigid arms.
- Discretization of shear walls.

### **3.3. Seismic Analysis Without Dissipators**

It consists of determining the response of the structure through the analysis methods established in Standard E.030. Static analysis represents seismic loads through a set of forces acting on the centre of mass of each level of the building. Spectral modal dynamic analysis allows determining lateral displacements, shear forces per level, stiffness, periods, and masses; the values of which will be verified with the permissible values according to Standard E.030.

### **3.4. Determination of the Objective Drift**

Performance levels describe a damage limit state. They represent a limiting or tolerable condition, established based on the potential structural and non-structural damage to the building, the threat to the safety of building occupants induced by this damage, and the building's functionality after the earthquake [7]. The limiting drift was selected based on the consideration of associating the structure with an operational performance level, where the limiting drift is 0.005.

### **3.5. Seismic Analysis with Dissipators**

It consists of determining the response of the structure with the addition of energy dissipators. The design to be carried out will be iterative; for this procedure it is only necessary to carry out a modal spectral dynamic analysis, in order to save the program's computing time. An adequate number of dissipators is proposed for each frame, these being modelled as NLINK type elements, since their use is more efficient and the structure is ready for a subsequent time history analysis.

### **3.6. Design of Decoupled Walls**

The design of decoupled walls is similar to the design of traditional shear walls, and will be carried out based on the provisions of Standard E.060. Decoupled walls must be designed for the simultaneous action of shear forces and bending moments, but not axial forces due to their particular condition

## **4. Case Study**

The building to be evaluated is the Anglo-American Clinic, whose project was drawn up in 1983, a 10-story building with a basement, intended for hospital use (Fig. 11).

### **4.1. Diagnosis of Structure State**

A test of environmental vibrations was carried out where a total of six points were taken in the upper levels using a Sara Geobox 24 Bit Triaxial digital seismograph (Fig. 8) to estimate the natural periods in each analysis direction. The Fourier spectra were calculated with the GEOPSY software, this software applies the fast Fourier transform to a signal in the time domain to convert it to the frequency domain. The amplitudes of each frequency are related to the amount of energy that this frequency contributes to the signal, so the peaks in the spectra are associated with the natural frequencies of the system.

The average H/V spectral ratio graphs were obtained – frequency obtained at levels 9 and 10 where two peaks can be observed: the peak of greatest amplitude, whose frequency is approximately 2.50 Hz, and a second peak whose frequency is approximately 1.15 Hz. (Fig. 6 and Fig. 7).

Using the predominant periods of the structure obtained by the vibration test, a comparative table was made with the periods obtained in the structural model carried out in ETABS (Table 1). The modelled structure shows periods greater than those obtained in the field. Conservatively, it was decided not to adjust the period of the modelled structure to the period obtained in the field. This will provide an additional safety margin when controlling the dynamic response of the structure with dissipators from the maximum values obtained from the analysis.

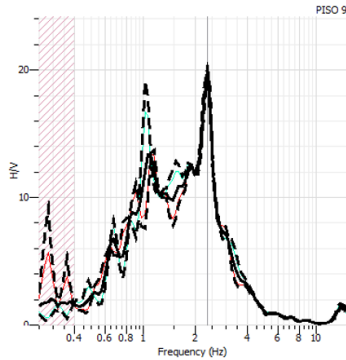


Fig. 6: Average H/V spectral ratio graph – frequency (level 9)

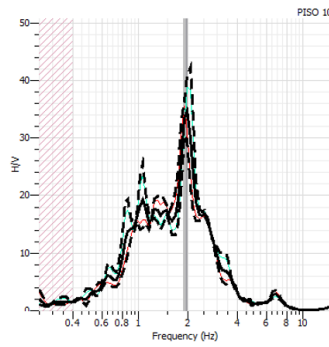


Fig. 7: Average H/V spectral ratio graph – frequency (level 10)



Fig. 8: Sara Geobox 24 Bit Triaxial Seismograph (Italy)

Table 1: Comparison of periods obtained by environmental vibration testing and ETABS model.

Description	$T_X$ (s)	$T_Y$ (s)	$T_R$ (s)
Environmental vibration test	0.860	0.860	0.460
ETABS model	0.996	0.926	0.673

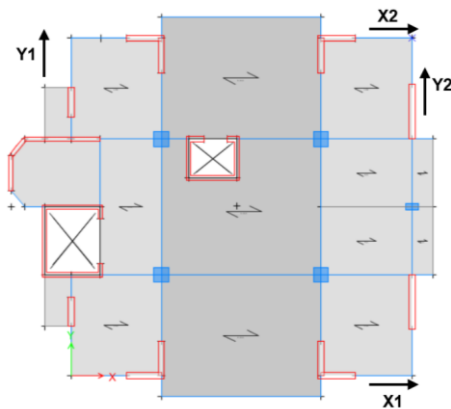


Fig. 9: Typical plan of structural model without dissipators developed in ETABS

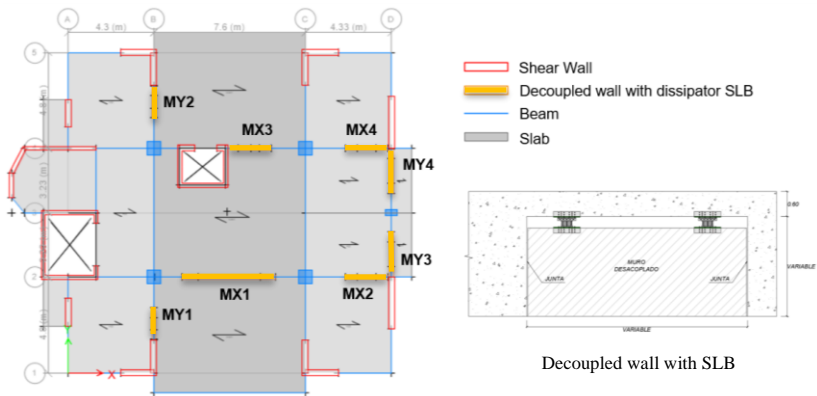


Fig. 10: Typical plan of structural model with dissipators and decoupled walls developed in ETABS



Fig. 11: Anglo American Clinic

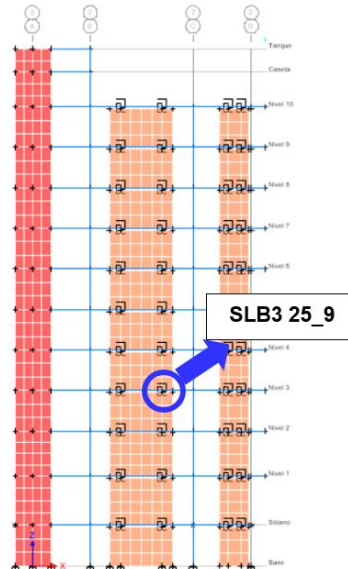


Fig. 12: MX1 (Elevation 2-2)

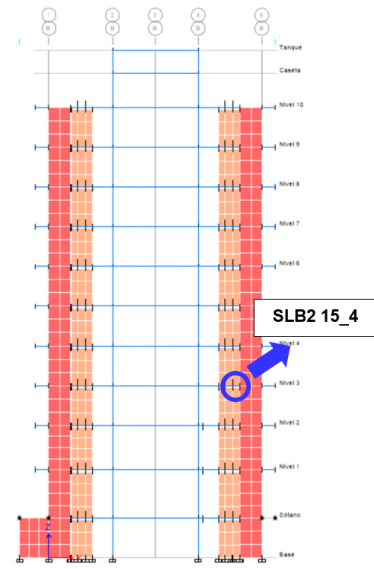


Fig. 13: MY4 (Elevation D-D)

Table 2: Drifts obtained in structural analysis without dissipators

Level	$\Delta X_1$	$\Delta X_2$	$\Delta Y_1$	$\Delta Y_2$
Level 10	0.00637	0.00539	0.00313	0.00644
Level 9	0.00692	0.00577	0.00351	0.00711
Level 8	0.00744	0.00610	0.00385	0.00783
Level 7	0.00785	0.00635	0.00412	0.00850
Level 6	0.00810	0.00646	0.00428	0.00901
Level 5	0.00815	0.00641	0.00433	0.00928
Level 4	0.00793	0.00614	0.00422	0.00923
Level 3	0.00726	0.00552	0.00389	0.00863
Level 2	0.00620	0.00463	0.00336	0.00738
Level 1	0.00381	0.00283	0.00209	0.00429
Max:	<b>0.00815</b>	<b>0.00646</b>	<b>0.00433</b>	<b>0.00928</b>

Table 3: Drifts obtained in structural analysis with dissipators

Level	$\Delta X_1$	$\Delta X_2$	$\Delta Y_1$	$\Delta Y_2$
Level 10	0.00316	0.00339	0.00375	0.00344
Level 9	0.00356	0.00374	0.00421	0.00378
Level 8	0.00400	0.00411	0.00461	0.00417
Level 7	0.00439	0.00444	0.00487	0.00450
Level 6	0.00469	0.00468	0.00498	0.00474
Level 5	0.00486	0.00479	0.00495	0.00486
Level 4	0.00483	0.00469	0.00471	0.00486
Level 3	0.00454	0.00431	0.00425	0.00467
Level 2	0.00424	0.00387	0.00364	0.00429
Level 1	0.00297	0.00259	0.00237	0.00272
Max:	<b>0.00486</b>	<b>0.00479</b>	<b>0.00498</b>	<b>0.00486</b>

#### 4.2. Seismic Analysis without Dissipators

Table 2 shows the inelastic drifts obtained in both analysis directions, with 0.00815 being the value of the maximum drift in the X direction and 0.00928 in the Y direction. In addition, the difference between the values of the drift in the Y direction can be seen, where the ratio between the maximum drift and the average drift of the ends of the structure in the analysis direction is greater than 1.30 at all levels, so it can be concluded that there is torsional irregularity.

Using the predominant periods of the structure obtained by the vibration test, a comparative table was made with the periods obtained in the structural model carried out in ETABS (Table 1). The modelled structure shows periods greater than those obtained in the field. Conservatively, it was decided not to adjust the period of the modelled structure to the period obtained in the field. This will provide an additional safety margin when controlling the dynamic response of the structure with dissipators from the maximum values obtained from the analysis.

### 4.3. Seismic Analysis with Dissipators

The energy dissipation system will consist of 20 cm decoupled walls in both analysis directions (Fig. 10). Inelastic drifts are shown in both analysis directions, whose values are less than the established limit of 0.0050 (Table 3). In addition, the drifts at the ends of the building are very close to each other, so it can be concluded that the structure will have a uniform displacement in both analysis directions and the torsional irregularity that was initially present was corrected.

For the design of the dissipators, the SLB3 25\_5 series was assigned for both analysis directions and 3 iterations were performed on average to obtain the most suitable dissipator at each level where the demand-capacity ratio is less than 1.50. A non-linear time-history verification was subsequently performed by selecting a total of 7 sets of matched seismic records, in order to achieve more accurate results, averaging the response.

Fig. 14 and Fig. 15 shows representative hysteresis curves of the dampers for each selected load case. The SLB3 25\_8 series damper in the MX1 decoupled wall whose maximum force is 46.81 ton and its maximum displacement is 0.31 cm. In the Y direction, the SLB3 25\_5 series damper was assigned whose maximum force is 34.46 ton and its maximum displacement is 0.27 cm.

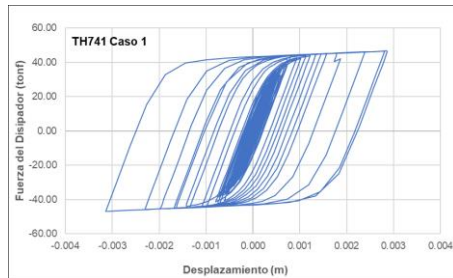


Fig. 14: Hysteresis curves of SLB3 25\_8 dissipator on decoupled wall MX1 (level 4)

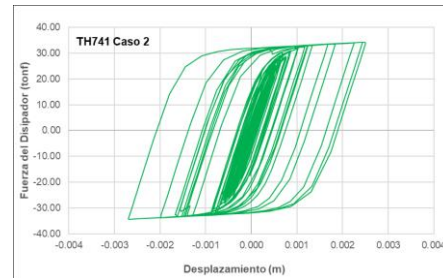


Fig. 15: Hysteresis curves of SLB3 25\_5 dissipator on decoupled wall MY2 (level 3)

The time-history verification was then carried out, where the drifts for each seismic recording case must be less than 0.00625 to conclude that the seismic analysis is adequate (Fig. 16 and Fig. 17).

Table 4: Seismic records considered for analysis

Code	Date	Station		Duration (s)	Component	a <sub>max</sub> cm/s <sup>2</sup>
		Name	Code			
TH66	October 17, 1966	Reserve Park (Lima)	PRQ	65.64	EW	180.56
					NS	268.24
TH70	May 31, 1970	Reserve Park (Lima)	PRQ	45.16	EW	105.05
					NS	97.81
TH71	November 29, 1971	Reserve Park (Lima)	PRQ	40.12	EW	53.66
					NS	86.21
TH741	October 3, 1974	Reserve Park (Lima)	PRQ	97.96	EW	194.21
					NS	180.09
TH742	January 5, 1974	Zarate (Lima)	ZAR	32.80	EW	138.94
					NS	156.30
TH01	June 23, 2001	Cesar Vizcarra Vargas (Moquegua)	MOQ001	198.91	EW	295.15
					NS	219.99
TH07	August 15, 2007	UNICA	ICA002	218.06	EW	272.82
					NS	333.66

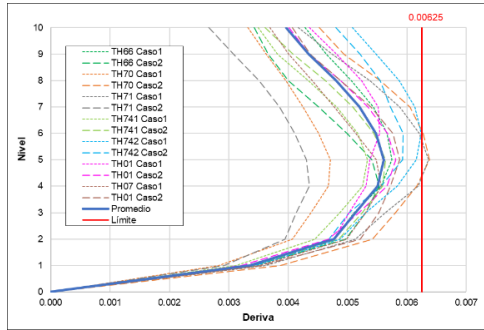


Fig. 16: Drifts in the X direction by seismic records

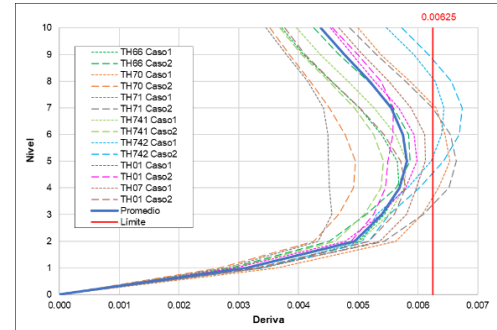


Fig. 17: drifts in the Y direction by seismic records

## 5. Conclusion

- The maximum drift in the X direction was reduced from 0.00815 to 0.00486 with the addition of the SLB dissipators, representing a 40% reduction. In the Y direction, the maximum drift was reduced from 0.00928 to 0.00498, representing a 46% reduction. Both drifts are within the limit that was established to ensure the functionality of the structure after a seismic event.
- Analysis using seismic records verified that the average of the drifts obtained for the seven selected seismic record sets is less than the established limit value. In the X direction, an average maximum drift of 0.0054 was obtained, and in the Y direction, an average maximum drift of 0.0058 was obtained, both values less than the established limit value of 0.00625.
- The proper location of the dissipators in the plan is important to correct structural irregularities. In the Y direction there was torsional irregularity, the relationship between the maximum drift and the average drift of the ends of the structure was 1.38. By adding dissipators, this relationship was reduced to 1.07, giving the structure uniform displacements.

## Acknowledgements

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